

GEODESIC NEIGHBORHOODS FOR PIECEWISE AFFINE INTERPOLATION OF SPARSE DATA

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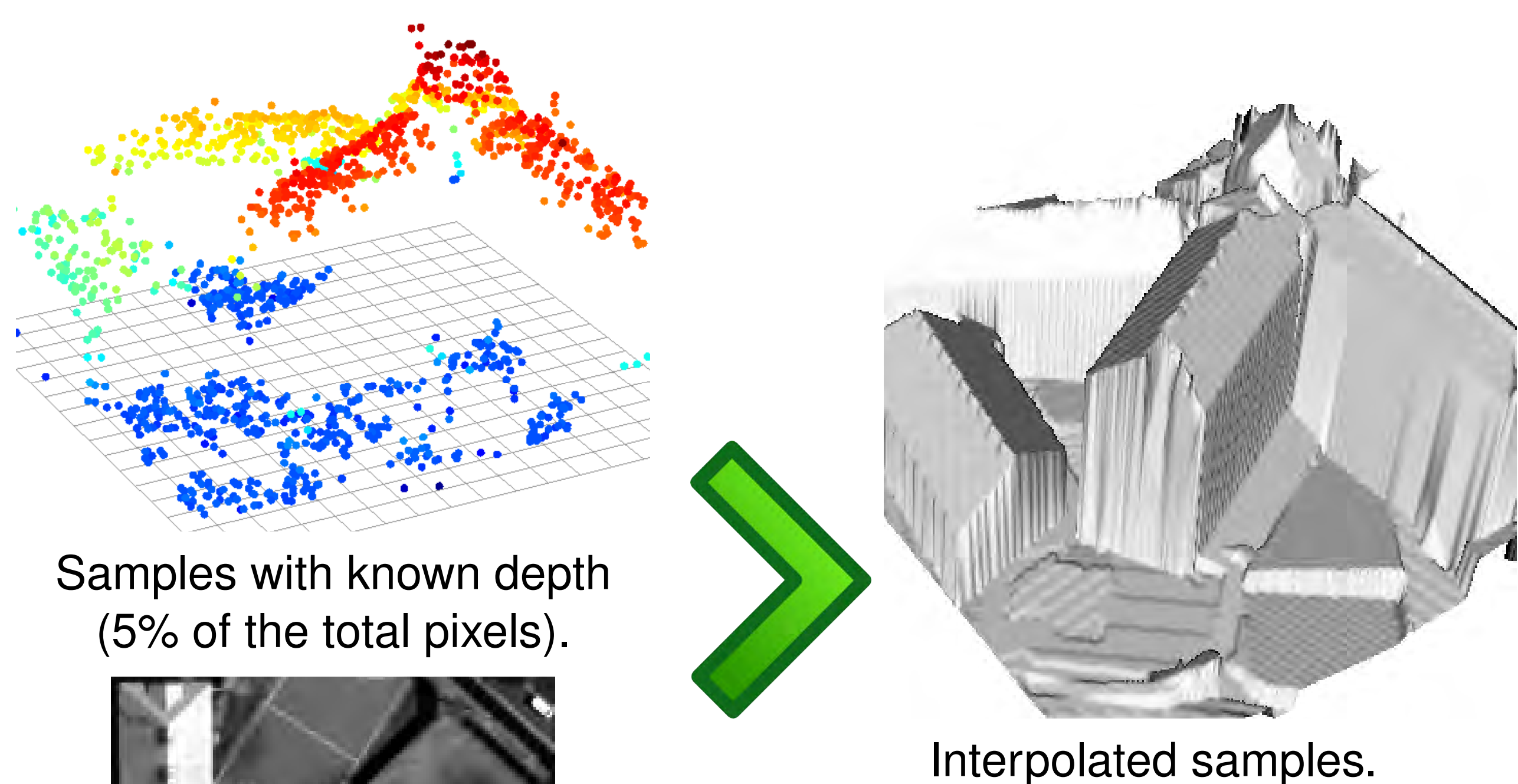
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Abstract

We propose a new interpolation method for sparse data that allows incorporation of geometric information of a reference image u . The idea consists in defining a geodesic Voronoi cell for each data sample, and fit a model to interpolate inside each cell. A geodesic distance permits both: to effectively adapt the shape of the cells to the image structures; and to compute a set of neighboring samples that are used for fitting a piecewise affine model at each cell.

Objective

Interpolate a set of range measurements (LIDAR or sparse disparity data [1]) using the additional knowledge provided by a photograph u of the scene.



Lambertian hypothesis: a uniform surface with a constant angle has a constant intensity in the image.

Allows to extrapolate information across uniform regions of the image.

Geodesic Voronoi Cells and Neighborhoods

We use the geodesic distance to incorporate the radiometric information provided by the image u into the interpolation as in [2].

Reference Image $u(x) : \Omega \rightarrow \mathbb{R}^+$, with $\Omega \subset \mathbb{R}^2$.

Positions of the samples $\Lambda \subset \Omega$.

Depth values of samples $G(\lambda) : \Lambda \rightarrow \mathbb{R}$, $\lambda \in \Lambda$.

Curve $C(p) : [0, 1] \rightarrow \Omega$, and $C_{s,t}$ curve connecting s and t .

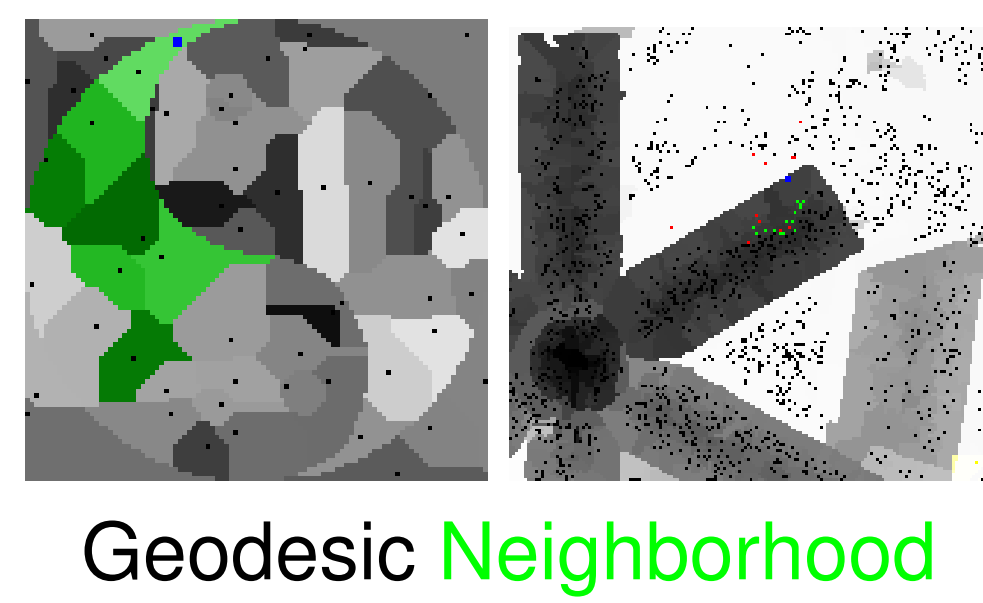
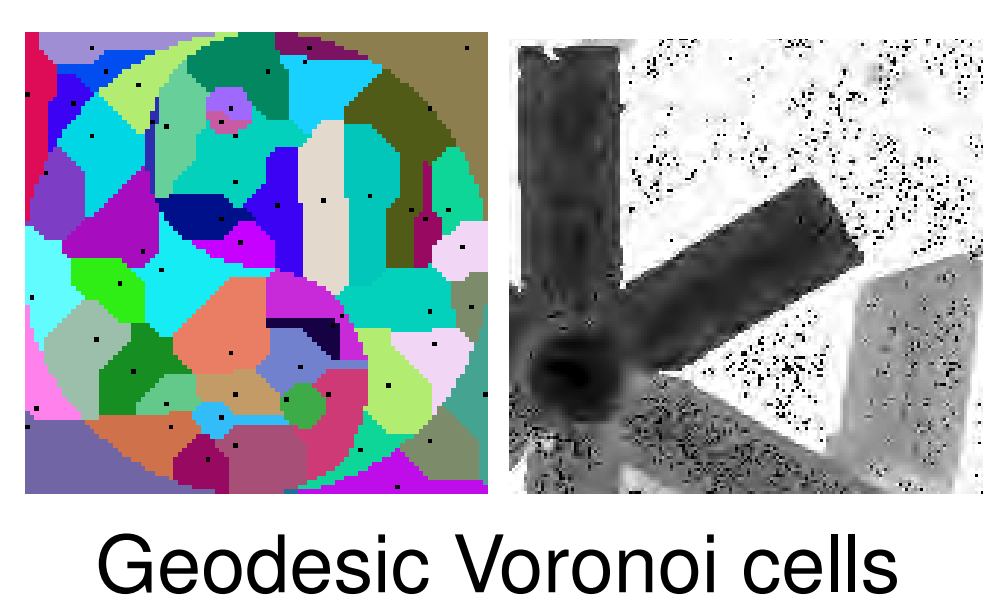
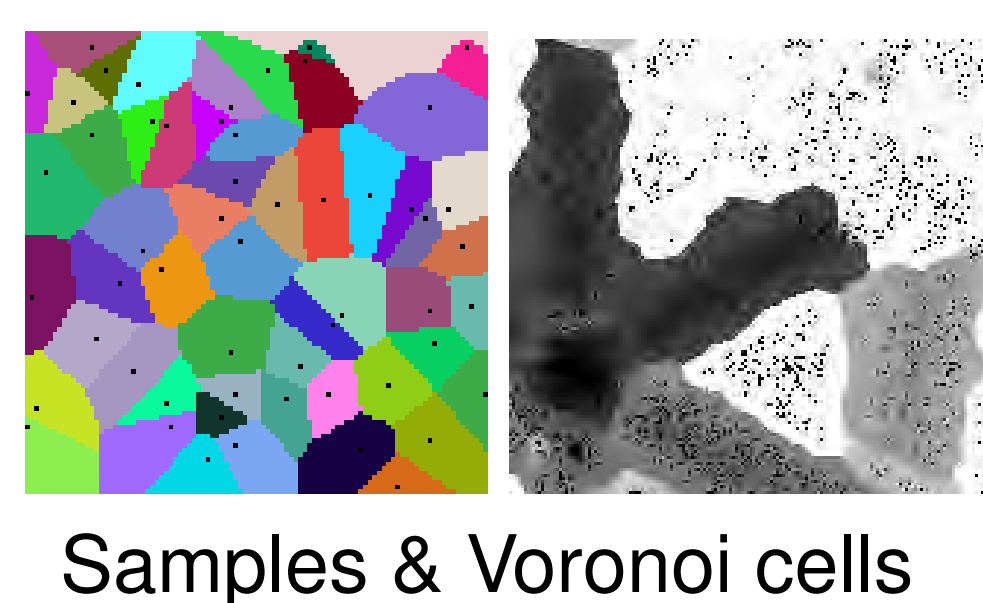
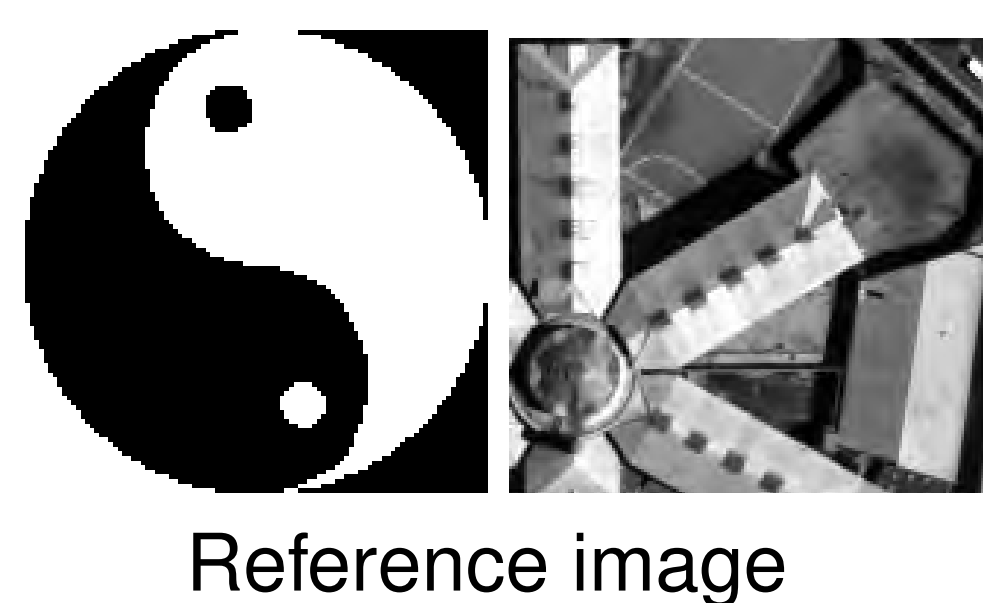
Geodesic distance between s and t measures the minimum variation of u between s and t

$$d(s, t) = \min_{C_{s,t}} \int_0^1 |\nabla u \cdot \dot{C}_{s,t}(p)| + \varepsilon |\dot{C}_{s,t}(p)| dp$$

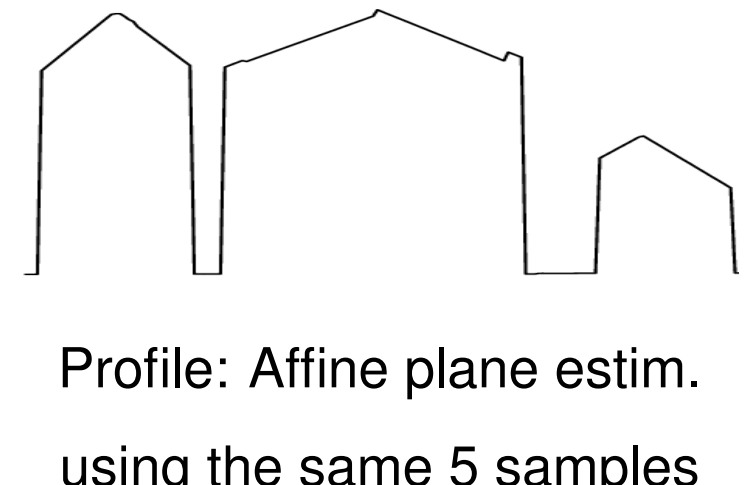
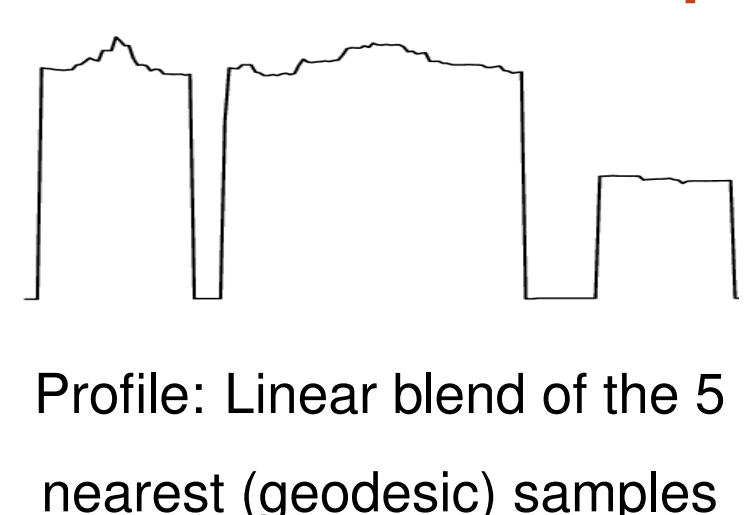
Observe: The shortest path is the one with less discontinuities of u along it.

Geodesic Voronoi diagram of the sites in Λ , successfully accounts for discontinuities in the image.

Geodesic neighborhood $GN_K(p)$ of the point p , is the set formed by the K -nearest (in the geodesic sense) samples of Λ to the point p . Samples in $GN_K(p)$ are likely to have the same model as p .



Robust affine plane interpolation using GN_K



For each point $p \in \Lambda$ we fit an affine plane through $GN_K(p)$. Then we extended the plane to the entire cell, **the initial piecewise affine model** H is the union of all the cells.

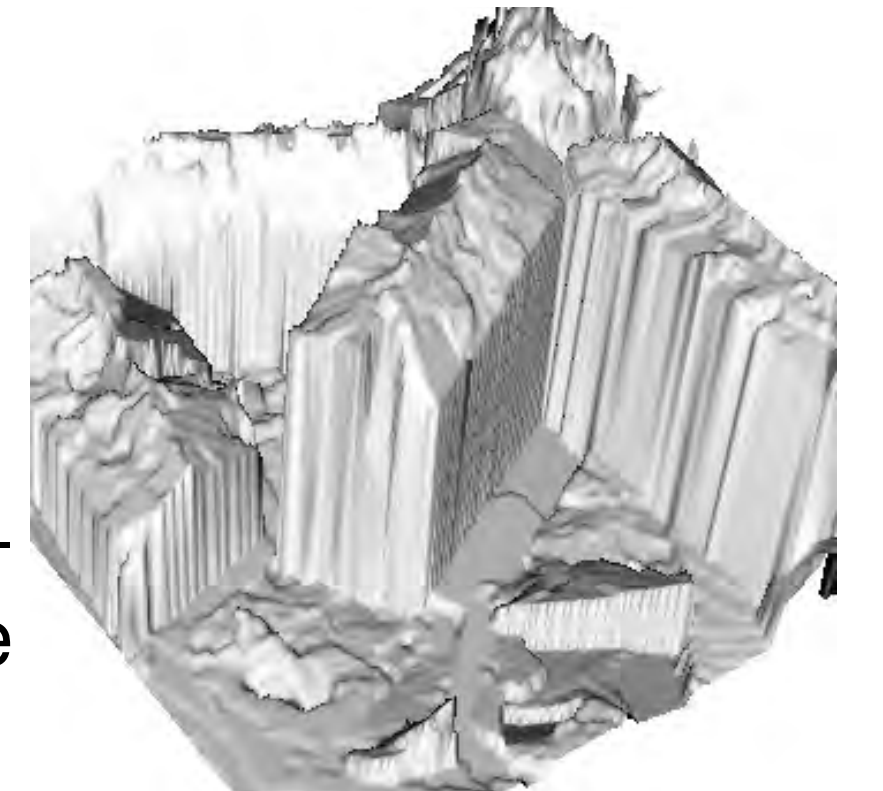
If $GN_K(p)$ contains outlier samples (that do not belong to the same surface as p) then the result will be biased. To remove these outliers we use a modified **RANDOM SAMPLE CONSENSUS (RANSAC)** [4].

Constrained region merging

Problem: When interpolating noisy data

- the model of each cell is independently estimated,
- adjacent cells may end up with different models.

Our solution: Merge adjacent regions with compatible models, and compute a common model to reduce noise effects.



Result without merging



Simplified Mumford-Shah [5] minimizes

$$E(B, f) = \sum_{R \in \mathcal{P}(\Omega)} R \text{Err}(R, f) + \lambda \int_B g(s) ds, \quad \lambda \geq 0.$$

- **Error term:** $R \text{Err}(X, f) = \sum_{x \in X \cap \Lambda} |f_X(x) - H(x)|^2$

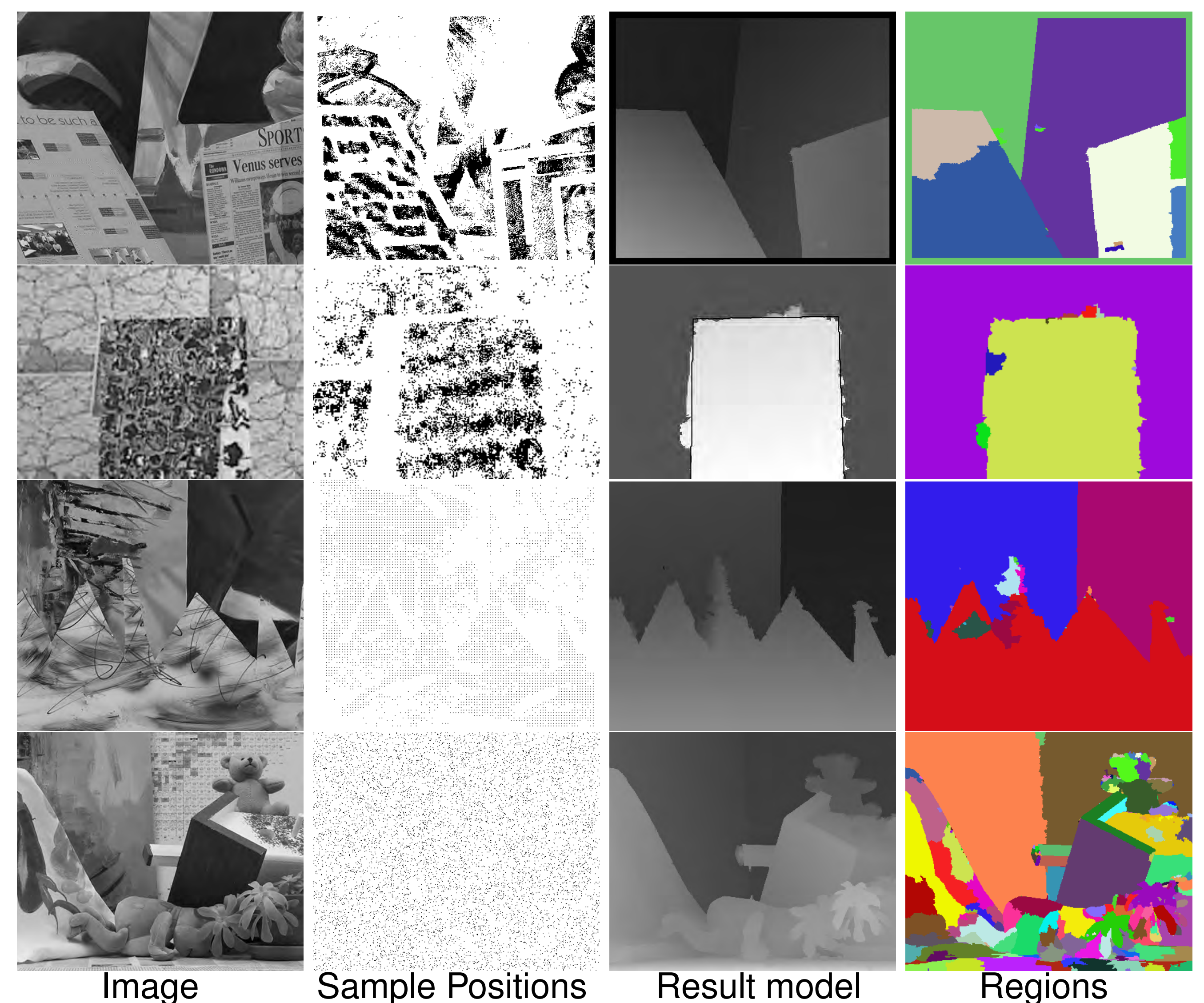
H : the initial plane interpolation

f_X : the affine model for the region X



- **Boundary length:** $g(s)$ is big at poorly contrasted boundaries and small at well contrasted ones.
- Also constrained by the segments of the original image [6].
- Greedy algorithm: merges pair of regions while the error term is small.

Results



Discussion

- Method for interpolating range data that incorporates the geometric information provided by an image of the scene.
- Geodesic neighborhoods constitute a fast and robust tool for modelling the local information, it can be adapted to other (non-affine) models [3].
- Poor results for badly contrasted edges between strongly textured regions.

More results at: <http://gpi.upf.edu/static/geoint>.

References

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6. R. Grompone, J. Jakubowicz, J-M. Morel, and G. Randall, "Lsd: a line segment detector on digital images," *IEEE TPAMI*, 2007.