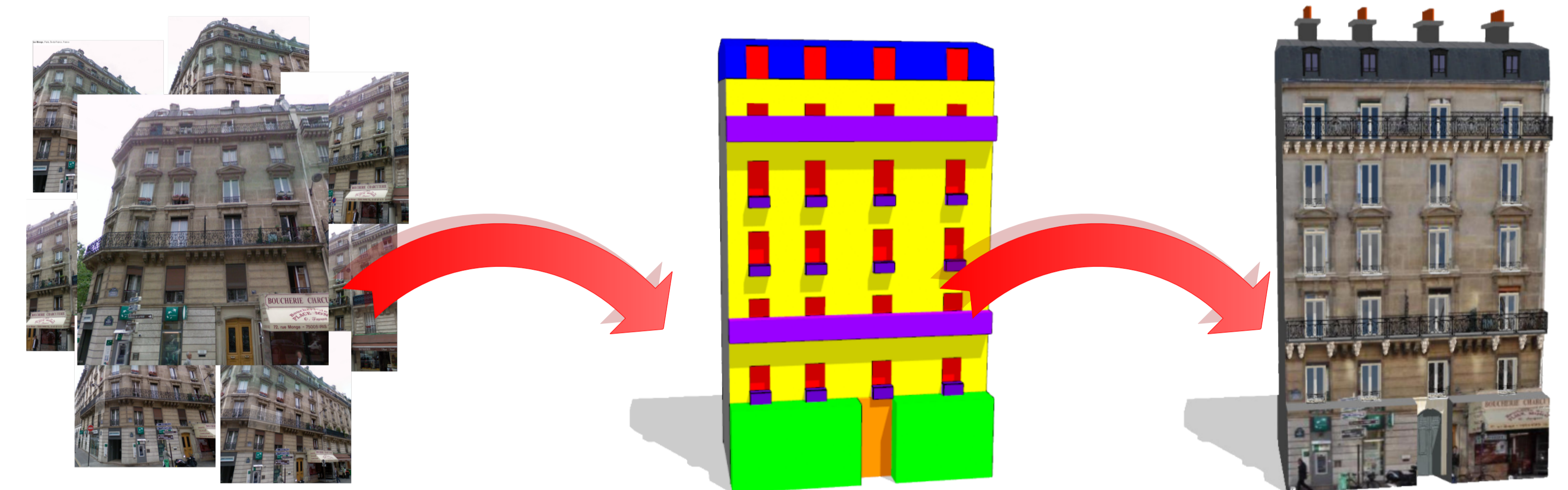


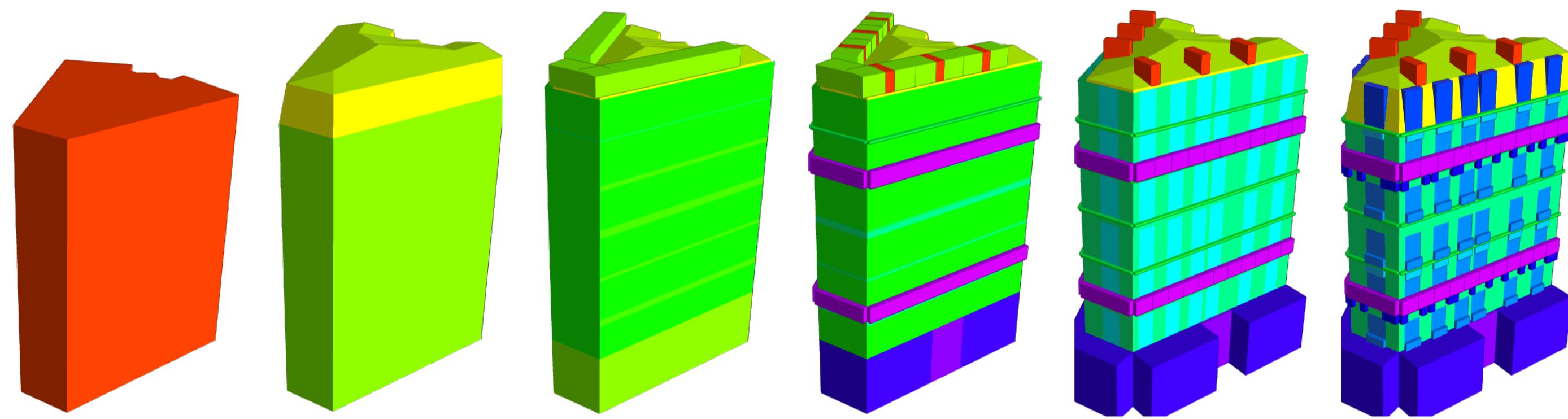
OVERVIEW

We address **multi-view reconstruction** of urban environments using **3D shape grammars**. Our formulation expresses the solution to the problem as a shape grammar **parse tree** where both the tree and the corresponding derivation parameters are unknown. Besides the grammar constraint, the solution is guided by an image support that is twofold. First, we seek for a derivation that induces optimal **semantic partitions** in the different views. Second, using structure-from-motion, noisy **depth maps** can be determined towards minimizing their distance from the ones predicted by any potential solution. We show how the underlying data structure can be efficiently optimized using **evolutionary algorithms** with automatic parameter selection. To the best of our knowledge, it is the first time that the multi-view 3D procedural modeling problem is tackled.

keywords: Multi-view reconstruction, Shape Grammar, Evolutionary Algorithms



SHAPE GRAMMAR REPRESENTATIONS [1]



DATA TERMS

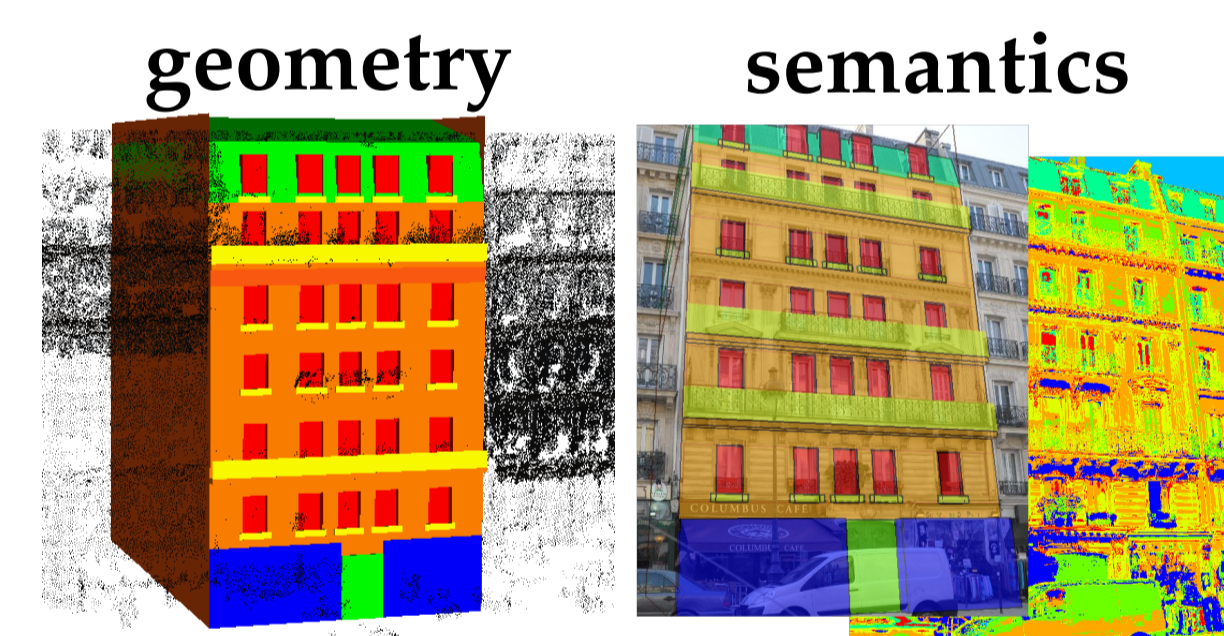
Two concurrent energies:

► **Depth cues** ↔ **geometry**

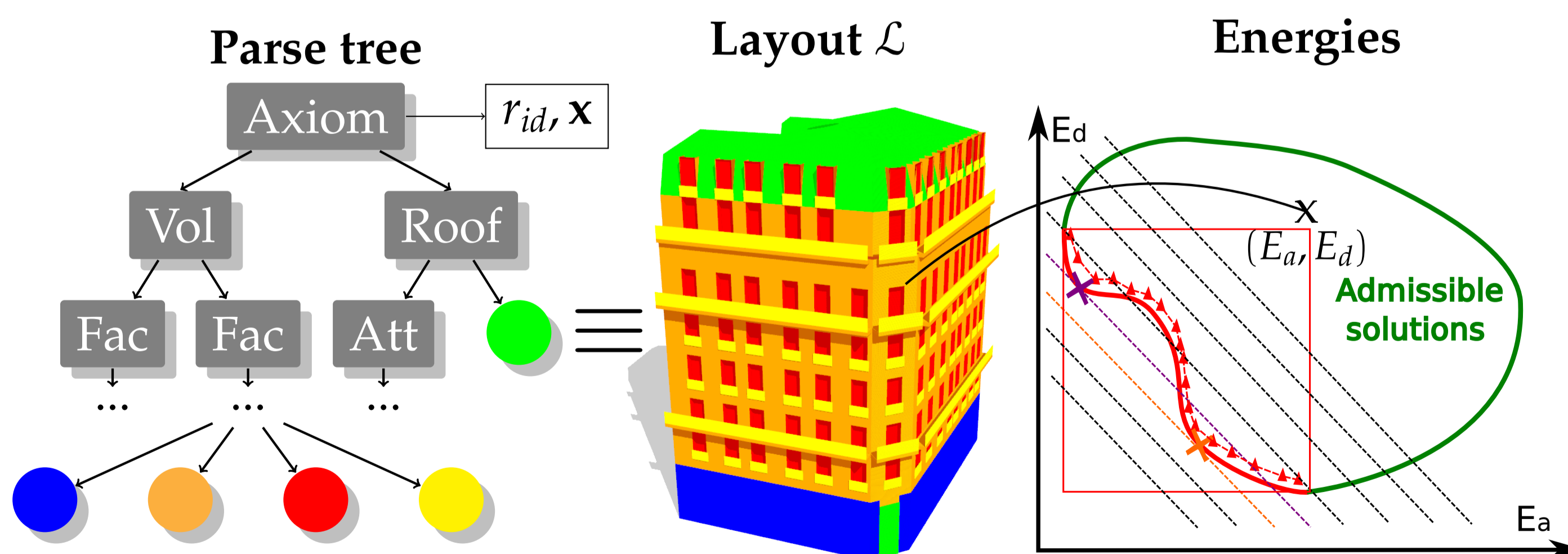
$$E_d(\mathcal{L}) = \sum_m \sum_x \|D_{\mathcal{L}}^m(x) - D_{ref}^m(x) - \bar{d}^m\|^2$$

► **Appearance cues** ↔ **semantics**

$$E_a(\mathcal{L}) = \sum_k \sum_x -\log P(I_k(x)|\mathcal{L})$$



INFERENCE



Difficulties:

- variable length description
- huge parse-tree
- discrete/continuous
- multi-objective

Goal:

- estimate **Pareto front**
- optimal solution

EVOLUTIONARY ALGORITHMS [2]

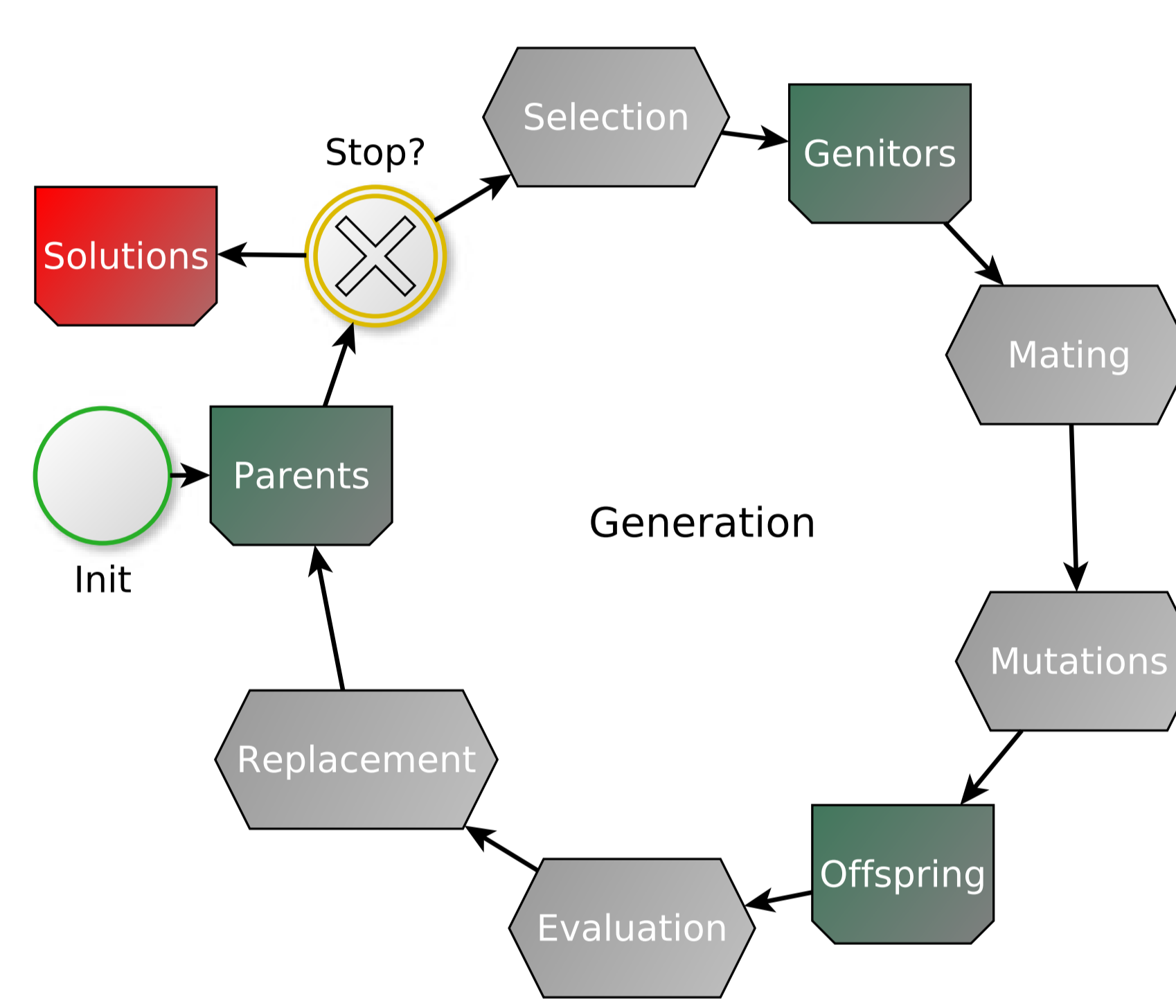


Figure: Typical pipeline of EAs.

Reconstruction context:

- **genotype:** parse tree
- **phenotype:** layout
- **fitness:** $(E_d(\mathcal{L}), E_a(\mathcal{L}))$
- **selection:** SPEA-II

Mutation of 1 tree:

- select a random node
- change r_{id} or x

Mating of 2 trees:

- select equivalent nodes
- swap content

⇒ Partial rederivation

RESULTS

Settings:

- 10 buildings with GT layouts \mathcal{L}_{gt}
- 2 views per facade
- OSM footprints
- Bundler+PMVS

Performance:

primitive	geometry	semantics					
window	11 cm	70	24	5	0	1	0
wall	4 cm	3	83	13	0	0	0
balcony	13 cm	10	7	82	0	1	0
door	1 cm	0	2	0	84	0	14
roof	31 cm	8	6	7	0	79	0
shop	27 cm	0	4	0	2	0	94

Reconstruction results



SPEA-II SELECTION & OPTIMAL SOLUTION

Inputs:

- P : current population
- A : archive of non-dominated solutions
- a : maximum size of archive

Outputs:

- P^* : genitors
- A : updated archive

Execute:

- $A \leftarrow$ non-dominated solutions of $P \cup A$
- if** $\#A < a$:
extend A with $(a - \#A)$ fittest in $P \setminus A$
- elsif** $\#A > a$:
remove $(\#A - a)$ most dense from A
- $P^* \leftarrow$ tournament selection on A

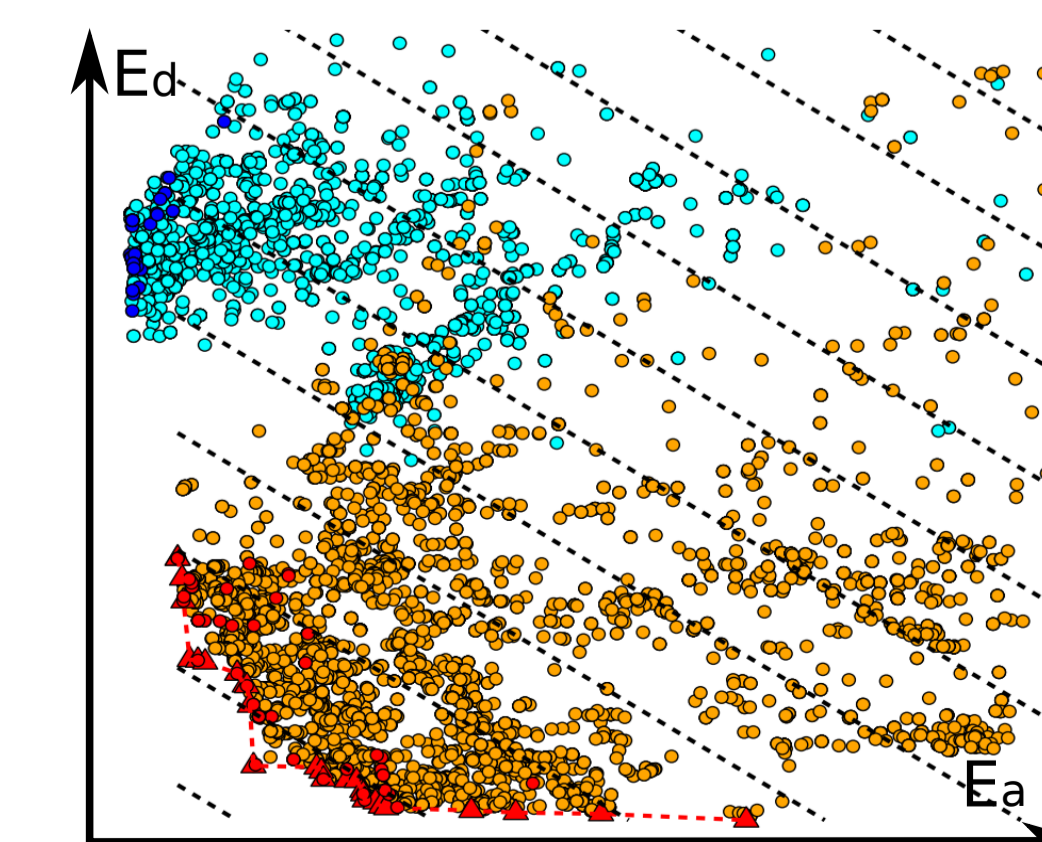
Optimal solution:

$$\mathcal{L}^* = \underset{A}{\operatorname{argmin}} E^\alpha(\mathcal{L})$$

where,

$$E^\alpha(\mathcal{L}) := \alpha E_a(\mathcal{L}) + (1 - \alpha) E_d(\mathcal{L})$$

SPEA-II vs tournament



CONCLUSION

Contributions:

- multi-view procedural reconstruction
- EA for grammar parsing
- multi-objective / automatic selection

Perspectives:

- data driven EA
- range data
- aerial

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